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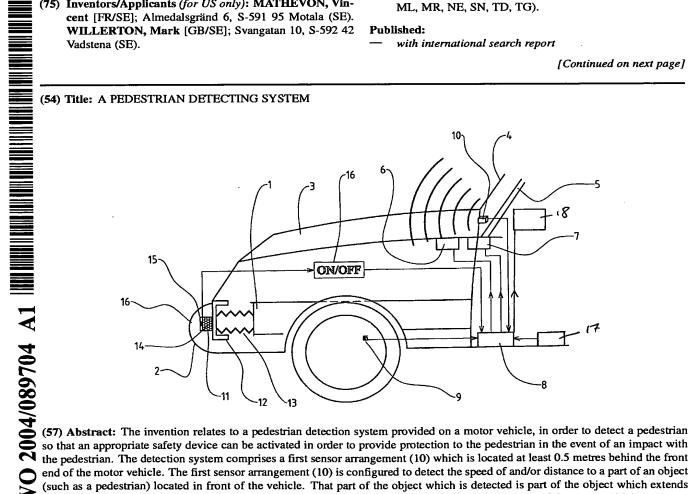
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end of the motor vehicle. The first sensor arrangement (10) is configured to detect the speed of and/or distance to a part of an object (such as a pedestrian) located in front of the vehicle. That part of the object which is detected is part of the object which extends above a predetermined height, which is at least the height of the front edge of the hood or bonnet (3) of the motor vehicle.



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